



High-Fidelity PIV of a Naturally Grown High Reynolds Number Turbulent Boundary Layer

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High-Fidelity PIV



Sound reproduction over full range of audible frequencies with very little distortion of the original signal

Naturally Grown High Reynolds Number Turbulent Boundary Layer



Complicated dynamic non-linear system



Boundary Layers 101

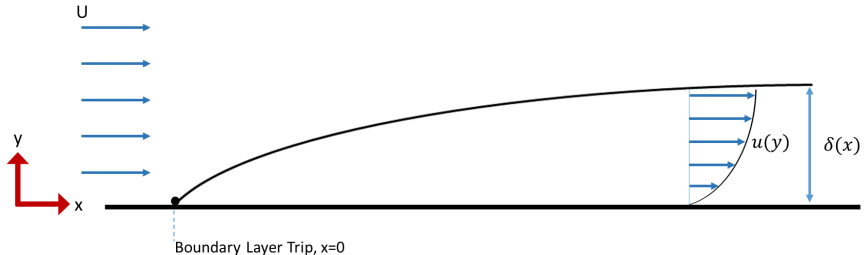
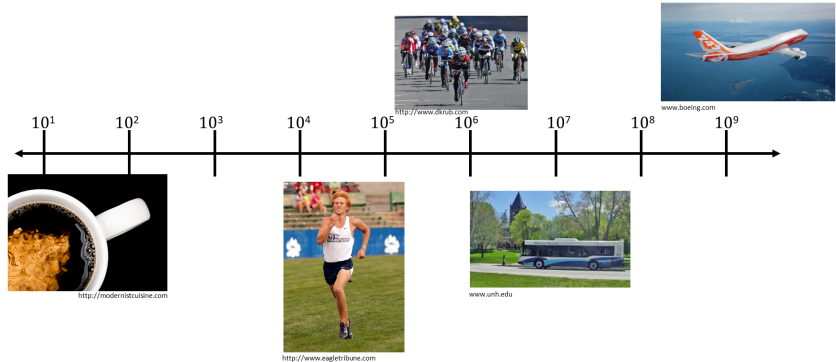


Image of mean boundary dynamics

Boundary layer thickness increasing with downstream position

Mean velocity profile staying self similar (ie when normalized indep. of position).

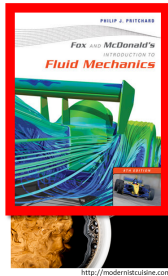
Reynolds Number Scales



► $Re = \frac{uL}{\nu}$

► $\eta = Re^{-3/4}L$
 η = small scales
 L = large scales

Reynolds Number Scales



10^3

10^4

10^5

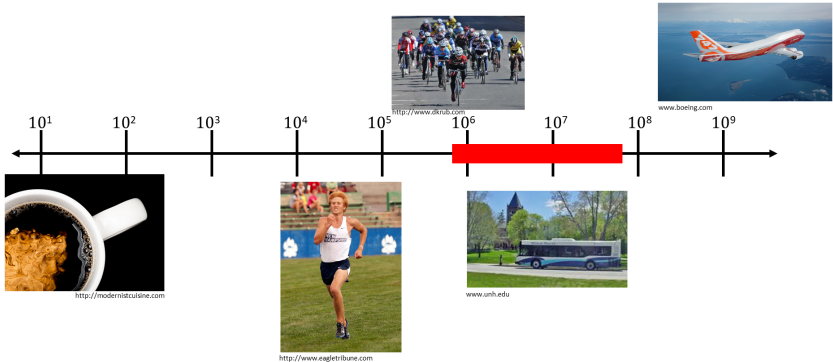
10^6



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Reynolds Number Scales



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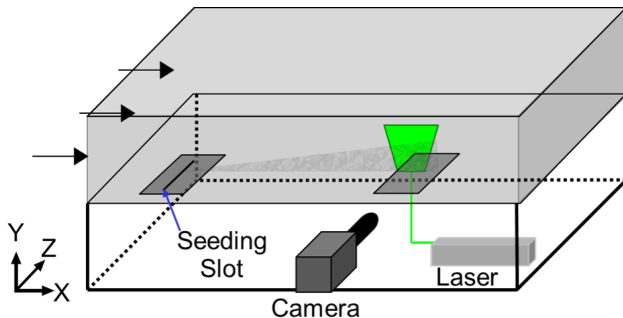
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Flow Physics Facility



- ▶ $2.8m \times 6m \times 72m$
- ▶ Driven by two $2.6m$ fans
-Each $400hp$
- ▶ Velocity: $3m/s$ - $14.5m/s$
-Vol. flow rate: $252m^3/s$
- ▶ Floor deviations: $.26mm/m$

PIV System: Overview



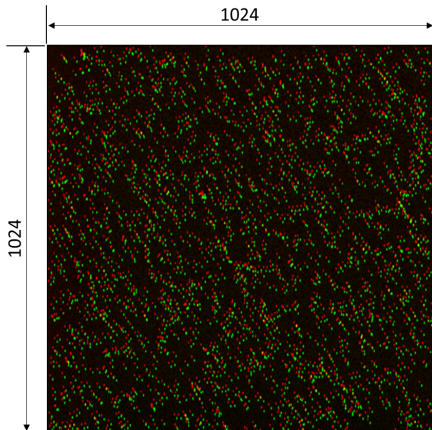
Photron Fastcam Camera

- ▶ 12bit
- ▶ CMOS
- ▶ 1024×1024 pixels
- ▶ $20\mu m$ pixel width
- ▶ $3.6kHz$ at full FOV

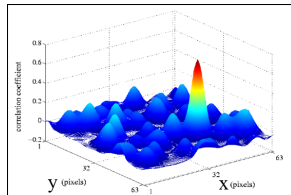
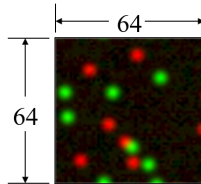
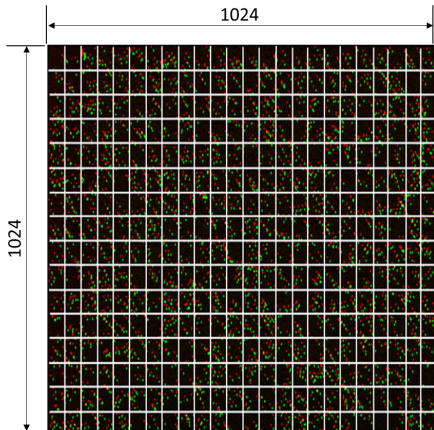
Photonics Nd:Ylf Laser

- ▶ $527nm$
- ▶ $30mJ/pulse$
- ▶ single shot - $10kHz$

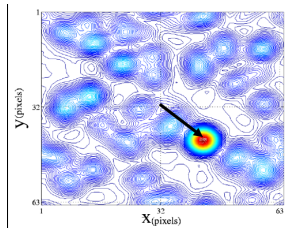
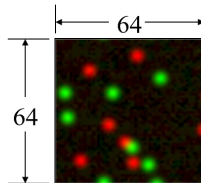
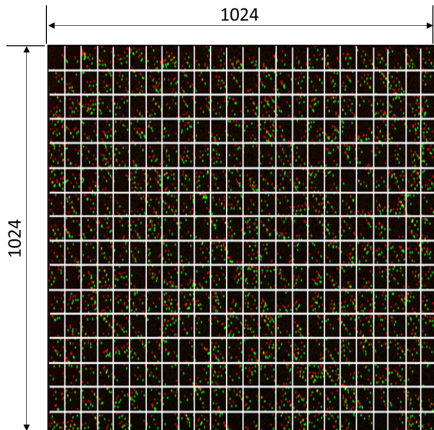
Processing Sequence



Processing Sequence



Processing Sequence



Imaging Sequence

Image A

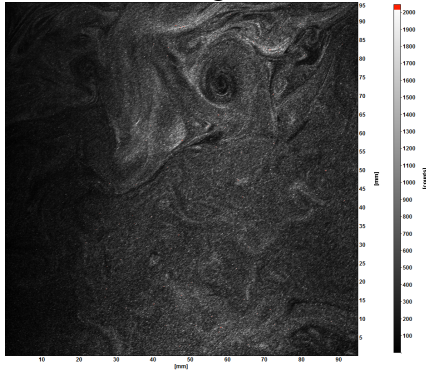
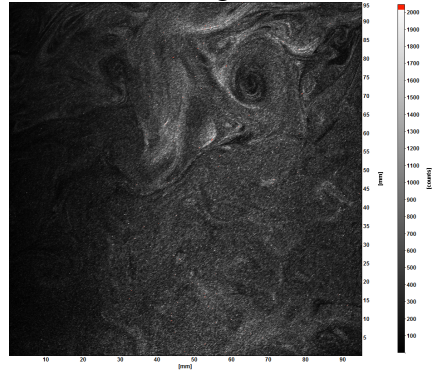


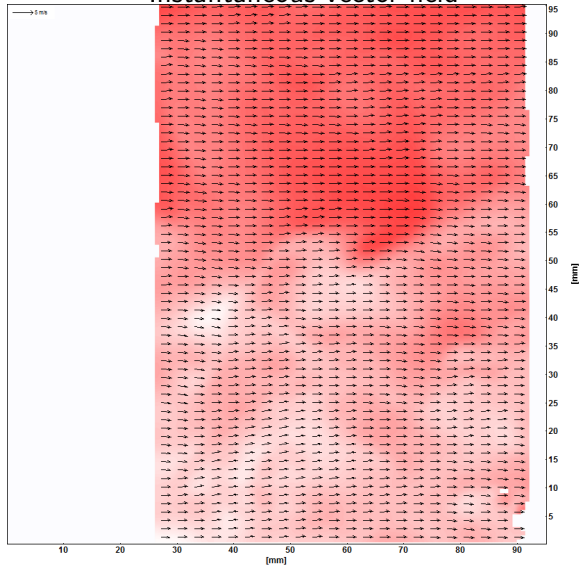
Image B



- ▶ images processed on multiloop scheme with decreasing interrogation window size

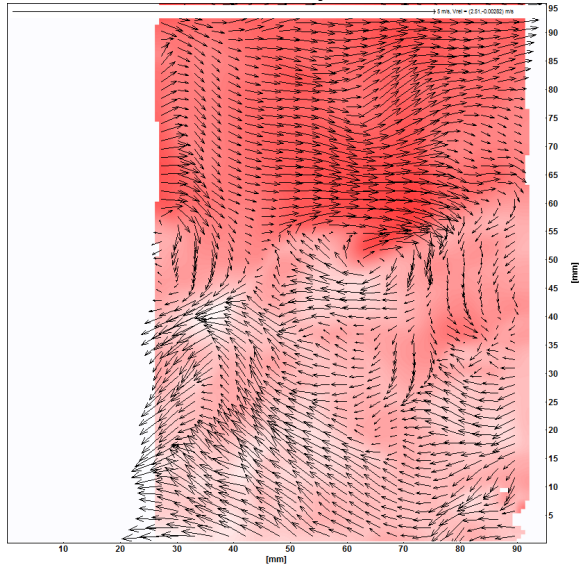
Imaging Sequence

Instantaneous vector field

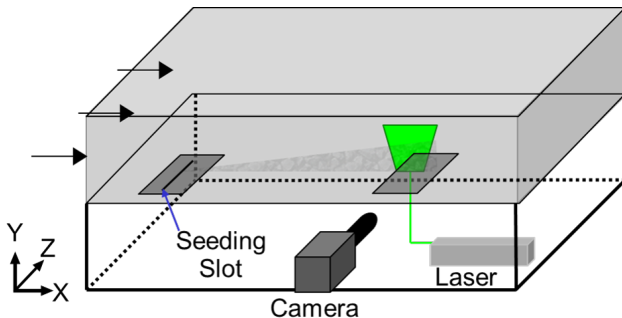


Imaging Sequence

Relative velocity vector field

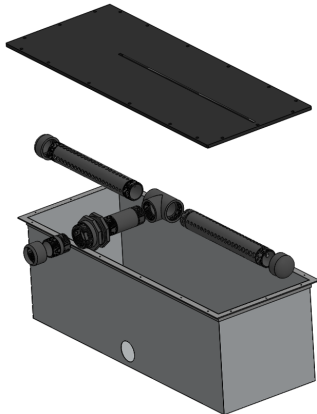


PIV System: Measurement Details



- ▶ Oil droplets : $1 - 5\mu m$
- ▶ Image plane $60m$ downstream
- ▶ $1m$ from laser sheet to camera
- ▶ $1.5mm$ laser sheet width
- ▶ $14m$ from injection slot to FOV
- ▶ FOV: $95mm \times 95mm$
- ▶ Magnification: $4.6 : 1$

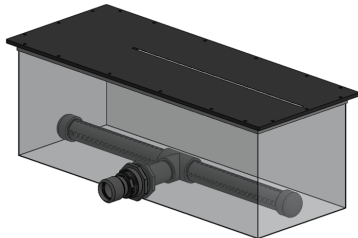
Seeder Mechanism



- ▶ 6mm slot width
- ▶ 1m slot length
- ▶ Slot angle 60°
- ▶ Inlet manifold to disperse fog
- ▶ Rosco fog machine



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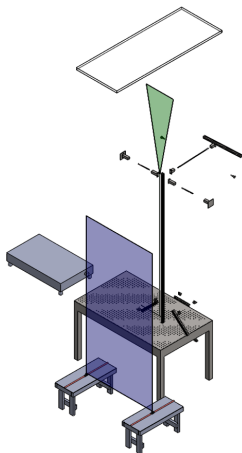
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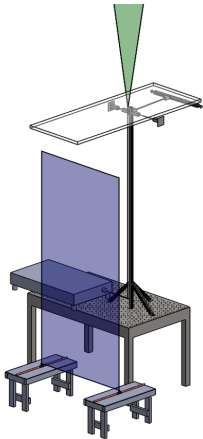


Laser / Optics Train



- ▶ Spherical focusing lens
- ▶ Cylindrical lens to create laser sheet
- ▶ Focused in center of FOV
- ▶ Adjustable to any window position

Laser / Optics Train



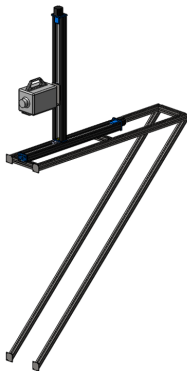
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Camera Setup



- ▶ Lowest wall normal position
- ▶ 200mm lens
- ▶ Magnification 4.6:1
(.09mm/pixel)
- ▶ Adjustable 30cm in y and z

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Flow Physics Facility



PIV Details and Processing

- ▶ 10,918 images at 600Hz
- ▶ final int. area: 16x16*pixels*
- ▶ $U_{\infty} = 4m/s$



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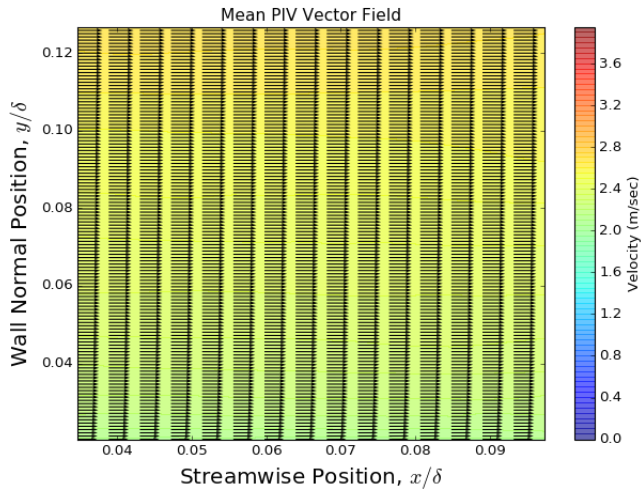
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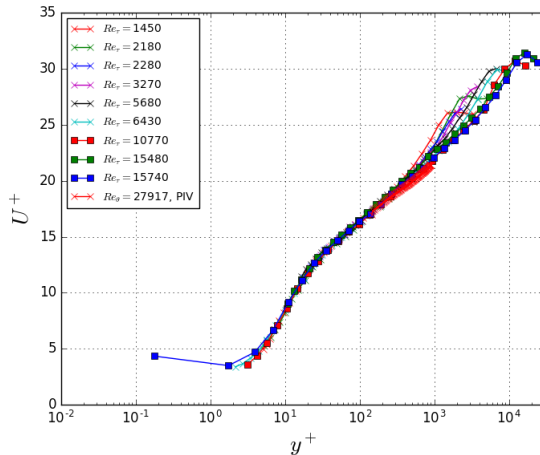
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Mean Velocity field

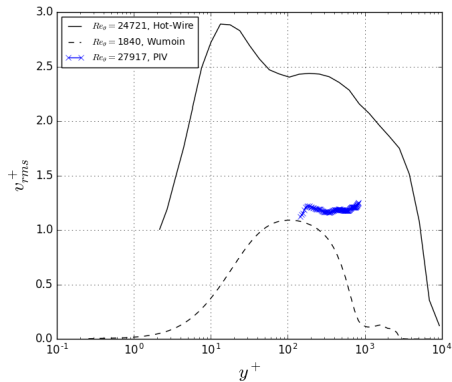
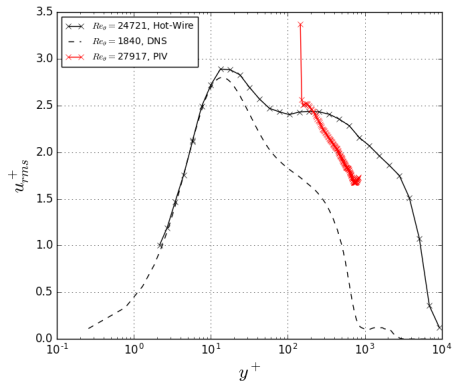


Mean Velocity field



$$y^+ = \frac{y u_\tau}{\nu}, \quad U^+ = U / u_\tau$$

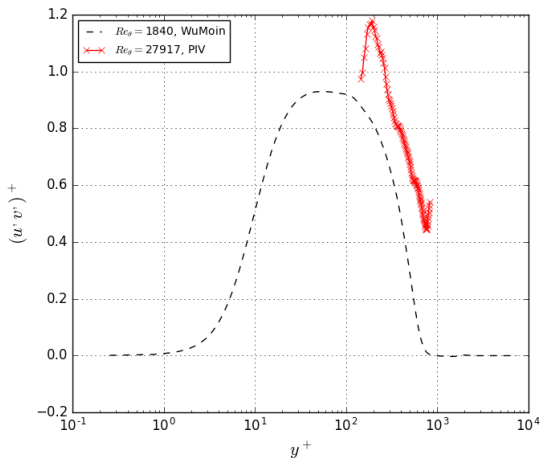
Mean Velocity field



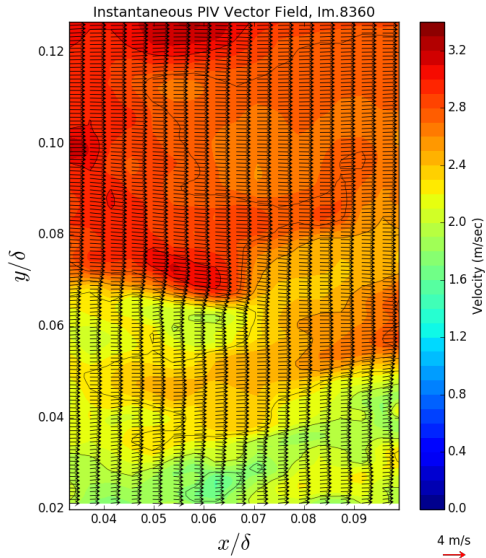
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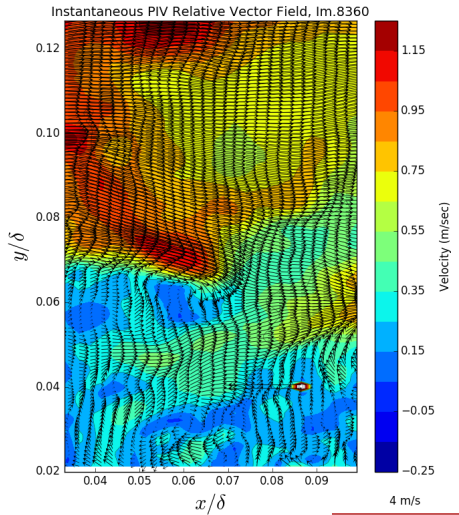
Mean Velocity field



Instantaneous Velocity: Structures

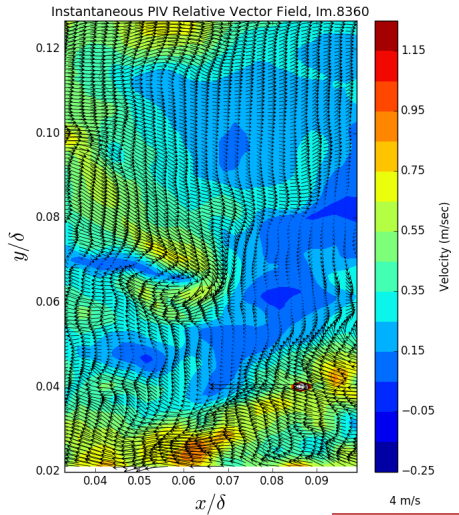


Instantaneous Velocity: Structures



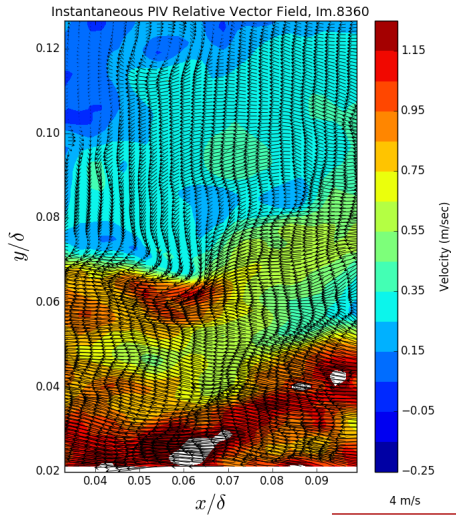
-Relative to $2m/s$

Instantaneous Velocity: Structures



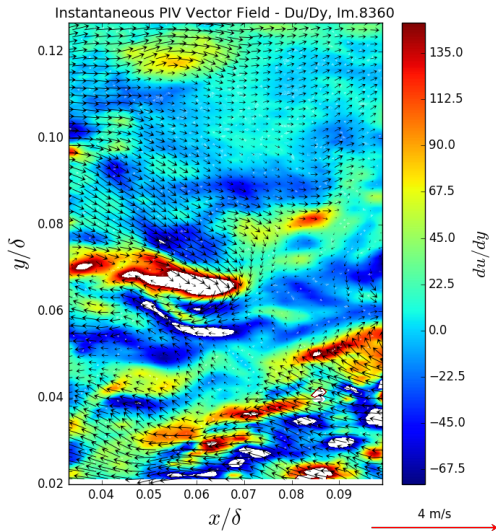
-Relative to 2.5 m/s

Instantaneous Velocity: Structures



-Relative to 3m/s

Instantaneous Velocity: Structures

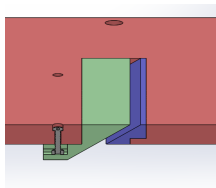


Summary

- ▶ Developed PIV system in high Reynolds number facility
- ▶ Captured time resolved PIV which represents the mean flow and beginning to resolve the first moment
- ▶ Beginning to develop method for examining for internal structures

To-Do

- ▶ Finish fabrication of new seeding slot



- ▶ Develop method (multi camera, stitching..) for expanded FOV



Thanks!